## Testing Quick Reference Handbooks in Flight Simulators

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# Preface

## Abstract

This is an abstract.

## Declaration

I declare that this dissertation represents my own work except where otherwise stated.

## Acknowledgements

I would like to thank my supervisor Leo Freitas for supporting, guiding, and providing with areas of improvement for me throughout the project.

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# Introduction

## 1.1 Scene

- Designing Emergency Checklists is difficult
- Procedures in checklists must be tested in simulators [1], which usually means trained pilots test it, as the tests need to work consistently [2] (making sure it's not lengthy, concise and gets critical procedures)
- Checklists are usually carried out in high workload environments, especially emergency ones

## 1.2 Motivation

- Testing procedures in checklists are often neglected [1]
- There are some checklists that may not be fit for certain scenarios e.g. ditching (water landing) checklist for US Airways Flight 1549 assumed at least one engine was running [3], but in this scenario, there were none
- Some checklists may make pilots 'stuck' not widely implemented, could be fixed with 'opt out' points. e.g. US Airways 1549, plane below 3000ft, could have skip to later in the checklist to something like turn on APU, otherwise plane will have limited control [3].
- Checklists may take too long to carry out Swissair 111

## 1.3 Aim

The goal of this project is to test checklists in Quick Reference Handbooks (QRH) for flaws that could compromise the aircraft and making sure that the tests can be completed in a reasonable amount of time by pilots. It is also crucial to make sure that the tests are reproducible in the same flight conditions and a variety of flight conditions.

## 1.4 Objectives

- 1. Research current checklists that may be problematic and are testable in the QRH tester being made
- 2. Implement a formal model that runs through checklists, with the research gathered to produce an accurate test
  - (a) Understand the relative states of the aircraft that need to be captured
  - (b) Ensure that the results of the checklist procedures are consistent
- 3. Implement a QRH tester manager that
  - Runs the formal model and reacts to the output of the formal model

- Connect to a flight simulator to run actions from the formal model
- Implement checklist procedures to be tested, run them, and get feedback on how well the procedure ran

# Background

## 2.1 Hypothesis

- Checklists can be tested in a simulated environment to find flaws in checklist for things like
  - Can be done in an amount of time that will not endanger aircraft
  - Provides reproducible results
  - Procedures will not endanger aircraft or crew further (Crew referring to Checklist Manifesto with the cargo door blowout)
- Results in being able to see where to improve checklists

## 2.2 Safety in Aviation

### 2.2.1 History

• 70-80% of aviation accidents are attributed to human factors [4]

### 2.2.2 Checklists

- Checklists have been shown to aid in minimising human errors [2]
- However, checklists can be misleading and compromise the safety of the aircraft due to them being either too confusing or taking too long to complete [1]
- That is why testing checklists are important to avoid these situations

## 2.3 Formal Methods

### 2.3.1 History

### 2.3.2 Application

## 2.4 Solution Stack

- There would be around 3 main components to this tester
  - Formal Model
  - Flight Simulator plugin
  - Checklist Tester (to connect the formal model and flight simulator)
- As VDM-SL is being used, it uses VDMJ to parse the model [5]. This was a starting point for the tech stack, as VDMJ is also open source.
- VDMJ is written in Java [5], therefore to simplify implementing VDMJ into the Checklist Tester, it would be logical to use a Java virtual machine (JVM) language.

### 2.4.1 Formal Model

- There were a few ways of implementing the formal model into another application
- Some of these methods were provided by Overture [6]
  - RemoteControl interface
  - VDMTools API [7]
- However, both of these methods did not suit what was required as most of the documentation for RemoteControl was designed for the Overture Tool IDE. VDMTools may have handled the formal model differently
- The choice was to create a VDMJ wrapper, as the modules are available on Maven

## 2.4.2 Checklist Tester

#### JVM Language

- There are multiple languages that are made for or support JVMs [8]
- Requirements for language
  - Be able to interact with Java code because of VDMJ
  - Have Graphical User Interface (GUI) libraries
  - Have good support (the more popular, the more resources available)
- The main contenders were Java and Kotlin [9]
- Kotlin [9] was the choice in the end as Google has been putting Kotlin first instead of Java. Kotlin also requires less boilerplate code (e.g. getters and setters) [10]

#### Graphical User Interface

- As the tester is going to include a UI, the language choice was still important
- There are a variety of GUI libraries to consider using
  - JavaFX [11]
  - Swing [12]
  - Compose Multiplatform [13]
- The decision was to use Compose Multiplatform in the end, due to time limitations and having prior experience in using Flutter [14]
- Compose Multiplatform has the ability to create a desktop application and a server, which would allow for leeway if a server would be needed

## 2.4.3 Flight Simulator Plugin

- There are two main choices for flight simulators that can be used for professional simulation
  - X-Plane [15]
  - Prepar3D [16]
- X-Plane was the choice due to having better documentation for the SDK, and a variety of development libraries for the simulator itself
- For the plugin itself, there was already a solution developed by NASA, X-Plane Connect [17] that is more appropriate due to the time limitations and would be more likely to be reliable as it has been developed since 2015

# **Design/Implementation**

## **3.1** Components

Splitting up the project into multiple components has been useful for

- Aiding in planning to make the implementation more efficient
- Delegating specific work tasks
- Making the project modular, for example, allowing for a different simulator to be implemented with minimal need to refactor other parts of the codebase



Figure 3.1: Abstract layout of components

Each of the components in section 3.1 will be covered in detail in this chapter.

## 3.2 Formal Method

- Formal modelling is the heart of the logic for testing checklists
- Formal model created using VDM-SL
- It allows to test that the checklists have been completed in a proper manner and that it is provable
- Model keeps track of
  - Aircraft state
  - Checklist state
- If an error were to occur in the model, this can be relayed that there was something wrong with running the test for the checklist, such as:
  - Procedure compromises integrity of aircraft
  - There is not enough time to complete the procedure
  - There is a contradiction with the steps of the checklist

#### Testing

- Since VDMJ version 4.5, it provides the QuickCheck tool
- This allows for providing counter examples to the model
- The counter examples were helpful to create pre and post conditions to avoid any unexpected results from the model

## 3.3 Checklist Tester

Brief overview of what it is supposed to do...

## 3.3.1 Designing

- Used Figma to create a design for the application
- Allows for implementing the front end to be faster because:
  - They act as a requirement for code
  - You do not forget what needs to be implemented
  - Keeps everything consistent
  - Allows to think about making parts of the GUI modular and what components can be reused
- Figma allows for plugins such as Material 3 colours and Material 3 components
- Figure 3.2 is the final design that will be used for the program

### Limitations of Figma

- The Material 3 Components in Figma do not include features that are available in Jetpack Compose
- In this project, the 'Simulator Test' at the bottom of Figure 3.2 does not include a leading icon [18], and therefore had to be a trailing checkbox
- This was overcome by adding comments in Figma as a reminder of how the actual implementation should be like
- Another limitation is that in Figure 3.2, the title of the screen in the top app bar [19] is not centered, and that is because the auto layout feature in Figma allows for equal spacing, rather than having each in a set position

## 3.3.2 Compose Multiplatform

#### Setup

- Used the *Kotlin Multiplatform Wizard* to create projects as it allows for runtime environments to be specified (in this case, Desktop and Server)
- Provides necessary build configurations in Gradle
- Planning what to implement important as Compose is designed to use modular components, otherwise a nested mess would occur as Compose is designed to have Composable functions passed in to a Composable function and therefore by design function nests will occur and the code will be harder to read if not managed correctly. Listing 3.1 shows example of using modular code from the Actions screen in project (with code omissions shown in comments)
- Used Voyager [20] to handle screens
- Used Koin [21] for dependency injection, to be able to get data from the database and VDMJ

	E Checkint Tester • smutate states •	Tratem       Tratem       Image: Image
	Checklist Tester () Smuther tables () Welcome! You currently have no projects	Brojects     Summarize trans
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Figure 3.2: Design for the Checklist Connector GUI in Figma

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- Chose to use it because of Voyager integration with Koin [22]
- Required as the application will be unresponsive when making requests to the database and/or VDMJ
- Used asynchronous coroutines to prevent the program from being blocked

## 3.3.3 Storing Data

- SQLD elight was used to handle the database by allowing for types afe Kotlin APIs when interacting with the database. Specifically chosen as it provides support for Compose Multiplatform [23]
- It only allows for queries to be written in SQL, which would allow for more complex SQL queries if needed
- SQLite was used for the Relational Database Management System (RDBMS) as it is an embedded database [24], meaning that the database will run in the application, rather than running on a server, either remotely or through local containerization through something like Docker [25], which could take more time and add complexity as it means implementing additional dependencies
- SQLite also has 100% [26] test coverage which is necessary for ensuring that the database will not cause artefacts to the results

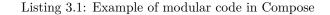
#### Designing the Database

- The database could be thought as having 2 sections
  - The user inputs to control the tester, i.e. the steps a procedure contains. The tables for these are *Project*, *Procedure*, and *Action*
  - The test results for a procedure which are in the Test, and ActionResult tables
- The design of the database had relationships in mind as the goal was to have a detailed tracking of statistics for each step in the procedure, hence in Figure 3.3
- A *Procedure* can have multiple *Tests*, where each *Test* each contains the result of how each *Action* in *ActionResults*
- The choice of a *Project* was to allow for the segregation of testing different aircrafts, as each aircraft has different cockpit layouts and different systems

#### Implementing into Compose Multiplatform

- Compose Multiplatform has support for different runtime environments, however as this project was only being developed for Desktop, the JVM SQLite driver only had to be considered
- However, the functions for the database were written in the *shared/commonMain* module as there may be a potential for adding Android and iOS support as it as it may be helpful run the tests on a tablet
- A database transaction had two modules
  - A class handling SQLDelight API calls only; meaning no conversion of types, which are functions only accessible within module internally, which is located in *io.anthonyberg.connector.shared.database*
  - SDKs that can handle multiple tables, such as *TestTransaction* which handles database calls when checklists are being tested in the application. And allows for converting types, such as **Int** to Long
- The separation of these modules was to have in mind unit testing, as it will make it easier to debug if a problem is with SQLD elight transactions are handled, or if there is a conversion error occurring

```
@Composable
1
    override fun Content() {
2
        // Content variables...
3
4
        Scaffold(
5
             topBar = {/* Composable content... */},
6
        ) {
7
             Column(/* Column option parameters... */) {
8
                 Box(/* Box option parameters... */) {
9
                      LazyColumn(/* LazyColumn option parameters... */) {
10
11
                          item {
12
                               Header()
13
                          }
14
15
                          items(
16
                               items = inputs,
17
                               key = { input -> input.id }
18
                          ) { item ->
19
                               ActionItem(item)
20
                          }
^{21}
                      }
^{22}
                 }
23
            }
^{24}
        }
^{25}
    }
26
27
    @Composable
^{28}
    private fun Header() {
29
        Text(text = "Edit Actions")
30
    }
^{31}
32
    @Composable
33
    private fun ActionItem(item: Action) {
34
        Column (/* Column option parameters... */) {
35
            Row(/* Row option parameters... */) {
36
                 Text(text = "Action ${item.step + 1}")
37
38
                 IconButton(/* IconButton definition parameters... */) {
39
40
                      Icon(
                          Icons.Outlined.Delete,
41
                          // Rest of Icon options...
42
                      )
43
                 }
44
             }
45
46
             Row(/* Row option parameters... */) {
47
                 OutlinedTextField(/* TextField definition parameters... */)
^{48}
49
                 OutlinedTextField(/* TextField definition parameters... */)
50
51
             }
52
            HorizontalDivider()
53
        }
54
   }
55
```



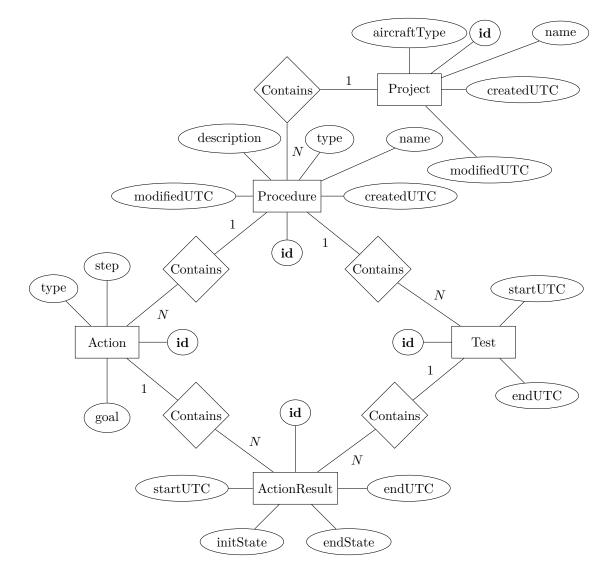


Figure 3.3: Entity Relationship Diagram for the database in Checklist Connector

### 3.3.4 VDMJ Wrapper

- VDMJ is written in Java and it is free open source software that is accessible on GitHub
- This allows for VDMJ to be used as per the license, GNU General Public License v3 (GPLv3) [27] [28]. This means that as VDMJ is being used as a library, the code for this project has to be licensed with GPLv3 or any GPLv3 compatible license [29]

#### Implementing VDMJ

- VDMJ has packages available on Maven Central making adding it as a dependency simple
- The package used was dk.au.ece.vdmj:vdmj with version 4.5.0
- However, initially when implementing VDMJ, 4.5.0-P was used accidentally and it led to debugging why imports were not working; and therefore the -P versions are not suitable
- The initial method of implementation was using a Ktor server that would have run alongside the desktop application, where the server would handle Representational State Transfer (REST) API calls
- This was unnecessary as the *interactive* mode of VDMJ was able to run on the desktop application itself. However, the Ktor was useful for debugging and testing as an API route was created to allow VDMJ commands to be executed through a URL
- To be able to get the outputs from VDMJ, a ConsolePrintWriter new had to be created from the com.fujitsu.vdmj.messages package; which handles writing to the console *stdout*. This then gets used to replace the Console.out and Console.err in the com.fujitsu.vdmj→ .messages package
- Parsing commands into VDMJ interface was more difficult <sup>1</sup>
  - Created a PipedInputStream object, that gets connected to a PipedOutputStream→ object by passing the latter object in as a parameter. The PipedOutputStream is then used to pass inputs into PipedInputStream
  - To be able to write to this stream, a BufferedWriter is created by passing the PipedOutputStream→ with a bridge OutputStreamWriter that encodes characters into bytes
  - For VDMJ to be able to read the input stream, a separate object had to be created, BufferedReader, where the PipedInputStream gets parsed through a bridge, InputStreamReader that converts bytes to characters

#### Handling VDMJ Outputs

- VDMJ outputs are handled using string manipulation
- Created into objects that are replicas of types in VDM-SL
- The string manipulation allows to specify where the outputs of the object go

#### 3.3.5 Connecting to the Flight Simulator

### 3.3.6 Testing

- Testing can be run with Gradle when it comes to running unit tests
- Decided to use JUnit 5 as it provides additional tools such as statistics, integration with IntelliJ to view code coverage, or being run in continuous integration tests
- The testable components in this project is mostly backend modules as the GUI made in Compose is not the focus of the project and it would require a lot of extra time
- Unit tests have been made for the database and Koin

<sup>&</sup>lt;sup>1</sup>The objects created here are provided by the java.io package.

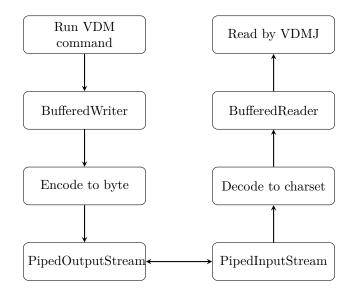


Figure 3.4: Flowchart of VDMJ Input/Output Stream handling

- Koin comes with tests that can be automatically be generated
- Ethos when testing was to try and find exploits, act as a user who may mishandle inputs, and stress testing functions by passing parameter with hundreds of objects

#### Testing for Resource Usage

- The application was tested using the *Profiler* tool on IntelliJ IDEA 2024 (Ultimate Edition) to find potential memory leaks
- One problem found was the initial VDMJ wrapper which would use the execute command instead of the interpreter, which would require reinitializing the entirety of VDMJ, which resulted in a slight memory leak and a massive write usage

## 3.4 Simulator Connector Plugin

## 3.4.1 Creating Maven Package

- XPC package is not published on a public Maven repository
- There has been a pull request that was merged to the *develop* branch that provides Maven POMs [30]. However, the maintainer for the project, at the time, did not have enough time to figure out the process of publishing the package to a Maven repository [31]
- Therefore, had to find an alternative way to implement
- Jitpack [32]
  - In theory, simple to publish a repository, all that is required is a GitHub repository and searching if one has already been created on JitPack or build and publish a specific version
  - However, due to the structure of the XPC repository, JitPack could not locate the build tools (Apache Maven in this case) as JitPack only searches on the root directory for the compatible build tools
- Gradle gitRepository [33]
  - There was not a lot of documentation
  - Ambiguous on how to define directory for where the Java library is located in the Git repository

- However, as XPC was only built with Maven, Gradle was not able add the dependency as gitRepository() only works with Gradle builds [34]
- Resorted to using a compiled Jar file and adding the dependency to Gradle
- Not happy about that because it means maintaining it will be more difficult as it is not as simple as just changing the version number
- Later, resorted to adding Gradle build files to XPC
- Used automatic conversion from Maven to Gradle using gradle init command [35]
- Had to add local dependencies due to how Gradle works differently
- Had to fix previous structure of Maven POM as the grouping as not good

#### Continuous Deployment of the Maven Package

- Used GitHub's template for Gradle package publishing
- Required some setup in Gradle build files

### 3.4.2 Submitting a Pull Request

- Adding the Gradle build tools can be seen as being helpful for others, as it would allow for the XPC library to be added as a dependency, especially if the NASA Ames Research Center Diagnostics and Prognostics Group were to add it to the GitHub repository, it would mean that it would be easier for people to access Maven Packages for XPC
- Therefore, to help improve the experience for other people who would want to develop with the XPC Java library, it would be logical to submit a pull request
- But it did mean making sure that the contribution would be perfect and not contain problems

#### Testing

- The XPC Java library includes a JUnit 4 test, however, implementing this with Gradle proved useless, as it was not able to get the results from the tests, which would be bad for not being able to catch problems with new builds
- Therefore, the tests were updated to JUnit 5, where most of the changes were adding asserts for throws [36]  $^2$

#### GitHub

- Made sure to add generated build files to .gitignore
- Changed the URL of the repository in Gradle to NASA's repository so that the Maven package can be published correctly on the GitHub repository
- From the beginning anyways, made sure to have insightful commit messages
- Submitted the pull request stating the changes made<sup>3</sup>

## 3.5 Scenarios

- Use a Quick Reference Handbook (QRH) to find potential list of checklists to test
- Look at previous accident reports that had an incident related to checklists and test it with my tool to see if it will pick it up
- These previous accident reports can be good metrics to know what statistics to look out for

<sup>&</sup>lt;sup>2</sup>The commit including the changes to the tests can be viewed here: https://github.com/smyalygames/ XPlaneConnect/commit/e7b8d1e811999b4f8d7230f60ba94368e14f1148 <sup>3</sup>https://github.com/nasa/XPlaneConnect/pull/313

## 3.6 Decisions

## Results

## 4.1 Final Prototype

### 4.1.1 Formal Model

- The model is mostly designed to imitate a Boeing 737-800, as the types modelled, have user inputs which are different from other aircraft types
  - For example, the Airbus A320 has push buttons whereas they are not there on the 737-800
  - However, further user input types could be added to the model and as a result, further aircraft types could have their procedures run through the formal model
- The **Procedure** type makes sure that the items on the procedure is completed in order, and if a step is missed, that would result in an invariant failure, resulting in the checklist test failing

### 4.1.2 Checklist Tester

- The main features of GUI have been completed, it has all the sections desired
  - Projects can be created to split up different aircraft or revisions of checklists
  - Procedures can be created and tested
  - These procedures get tested in the flight simulator automatically and gives the results of how the procedure has been doing in real time

#### 4.1.3 Setting up Tests

- Each test is set up by defining each action in the procedure, on the Procedure screen
- To be able to define each action is supposed to do, it uses the Dataref variables in X-Plane, which is what stores the state of the aircraft. Each switch has their own unique Dataref
- In the checklist tester then, each action asks for a Dataref and a desired goal value
- Some Datarefs are read only, but there are other Datarefs for the item desired, but are only 'command's, which can only be called and not have its value changed; this can be run by setting the desired goal value to be -988 (because XPC uses that value)

#### **Running Tests**

- Tests are run by connecting to the flight simulator, X-Plane
- The tester goes through each action in the procedure one by one and waits for the current action to complete before proceeding on to the next one
- The checklist tester is not advanced enough to be able to control fly the aircraft; hence the tester would be able to engage autopilot first, or control the aircraft themselves, where the checklist tester would be acting like a first officer

#### Storing Test Results

- There is a database storing the results of each of the tests
- Each tests store

**Time taken** for each of the actions in the procedure to complete **Start state** for the state that the action in the procedure was at

End state for the state that the action in the procedure finished the item at

Overall test time Stores the time taken from when the test started to when the test ended

• This gives feedback/statistics for the checklist designers to find areas of improvement on the procedure, such as one action in the procedure taking too long, may point out a potential flaw to the designer and as a result aid finding potential alternative options for that step in the procedure

## 4.2 Problems Found

## 4.3 LOC?

## 4.4 Reflection

### 4.4.1 Planning

#### Gantt Chart

Used Gantt chart to create a plan for what would be needed from this project

Pros:

- Was useful for the first part because it set expectations of what was needed and how much time there was to complete them
- Helped visualize the different components of the project
- Helped in the beginning being accompanied by a Kanban in Leantime<sup>1</sup>

#### Cons:

- Was not detailed enough, and a design document would have been useful to accompany the Gantt chart for each section
- The lack of detail was not helpful when falling behind as having attention deficit hyperactivity disorder (ADHD) added to the burden of feeling like each section was a massive project
- Leantime's claim for being 'built with ADHD [...] in mind' felt misleading as navigating through it felt worse than using the front page of Stack  $\rm Overflow^2$
- Todoist<sup>3</sup> was a good alternative though

#### **GUI** Design

Figma was very useful in implementations as

Pros:

- It helped with timing and knowing what to do
- Made things feel manageable as it was split up to different sections
- Meant features will not be forgotten

Cons:

- Certain features being too simple and annoying to use
- A bit of a learning curve for using other components, compared to using plugins

<sup>&</sup>lt;sup>1</sup>https://leantime.io/

<sup>&</sup>lt;sup>2</sup>https://stackoverflow.com/

<sup>&</sup>lt;sup>3</sup>https://todoist.com/

## 4.4.2 Implementation

#### **Checklist Tester**

- Implementing the GUI was useful to split up the sections required for the project and having a goal for what to be done
- However, a bit too much time was spent on creating a GUI when it could have been used for development
- It was useful for motivational reasons to feel like something materialistic has been produced rather than something theoretical
- Was originally intended to be used to interact with custom plugin for X-Plane as it would have been difficult otherwise

#### Connecting to the Flight Simulator

- Would have been more useful to search a bit further if there was another plugin available, as found Dataref Editor on the X-Plane docs, so could have looked for a similar plugin for connecting to X-Plane
- At first spent about a week developing a C++ X-Plane plug in from scratch, requiring to figure out sockets
- At the same time finding out XPC exists and having wasted that time
- However, it did teach me more about understanding how sockets work and more about C++ and setting up a project with CMake and adding packages with vcpkg

## 4.5 Time Spent

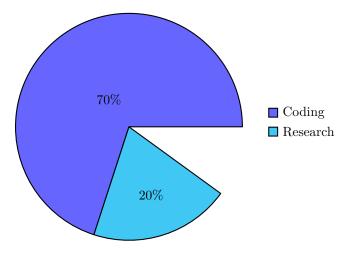


Figure 4.1: Time spent on sections of project

# Conclusion

## 5.1 Changes

- Added the checklist manager which was not a part of the original objectives
  - Helped more to visualize the project
  - Aided in gathering statistics for how well the checklist performed
  - Using Kotlin helped speed up development, it simplifies parts of Java and omitted a lot of boilerplate code that is required in Java, such as setters and getters
- How the Formal Model would interact was modified
  - Initially was designed so that the formal model would complete the entirety of the checklist, however, it was not useful for interacting with the flight simulator
  - Modified the model to provide it would be similar to actions pilots can do in the cockpit
  - Therefore acts like Read Checklist  $\rightarrow$  Pilot Logic (VDM)  $\rightarrow$  Do Action (XPC)
- Originally was supposed to write an original plugin to connect to the flight simulator
  - Whilst creating the plugin, sockets were confusing and accidentally stumbled on the X-Plane Connect GitHub repository
  - This could have been prevented if a design document was created and time was spent researching for tools in obscure places

## 5.2 Objectives

- Most of the objectives were met
- One of the original objectives was to research pilot reaction times and how long it takes pilots to complete an action
  - However, not able to do that as there are too many factors that can affect a pilot's reaction time, such as age, experience on an aircraft, total experience, how far a button is from the pilot, etc.
- Objective 2.a. was met to an extent
  - Currently, the states of the aircraft monitored are only the actions specified in the test, in the checklist tester
  - There could be more variables that could be monitored. Such as engine fire, could monitor the engine temperature or thrust produced by engine
  - This would have required a substantial amount of planning as checklists does have a bit of logic like if statements, for example 'If APU is available, then do ...else do ...'
- Objective 2.b. was also met to an extent

- Currently, this can be met by re-running the test multiple times manually
- However, it is manual at this stage due to limitations of XPC and setting up the aircraft
- The test data is stored on the database, hence test results can be analysed to see the consistency between each test
- The Checklist Tester does not currently run actions from the Formal Model due to implementing the functions from VDMJ being laborious
- Hence focus was put on XPC first, as it would produce direct results

## 5.3 What Next

The most important next steps to implement would be linking the formal mode, adding options of what parts of the aircraft to monitor

- Formal Model
  - Implemented either by creating an automatic wrapper. Done by either potentially linking the VDMJ LSP, or creating a plugin for VDMJ
  - Or doing string manipulation on the VDM results for each of the functions as a lot of it is copy and paste - can be bad practice as it requires a lot of hard-coded code
- Monitoring more of the aircraft
  - Done by adding options in the Checklist Tester for extra Datarefs to monitor
  - Modifying the Aircraft record type to include a states type that checks multiple times throughout the procedure if this state has violated a constraint or if the goal of the state has been achieved (e.g. Engine is no longer on fire)
- Expanding out of the scope of the objectives, adding logic, such as the if statements to the checklist would be the next logical step
  - VDM-SL would be really helpful for this, as can be used to design logic to be used outside of Kotlin
  - This would allow for further automation of checklists, rather than only testing linearly, which at this current state would require writing the test multiple times
- Adding more detailed test results
  - Use analysis of previous test results to gain an understanding of the reproducibility of the procedure
  - Keep track of aircraft state, such as speed or altitude aiding in understanding if the procedure may impose a safety risk

## Appendix A

# Formal Model

```
1 module Checklist
2 exports all
3 definitions
4
5 values
6
       -- Before Start Checklist
7
       -- Items in Aircraft
8
       -- Flight Deck... (can't check)
9
       fuel: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, false)→
           ):
10
       pax_sign: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, →
           true));
       windows: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<ON>, →
11
           false));
12
       -- Preflight steps
       acol: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, false)→
13
           );
14
       aircraft_panels: Items = {"Fuel_Pump" |-> fuel, "Passenger_Signs" →
15
           |-> pax_sign, "Windows" |-> windows, "Anti⊔Collision⊔Lights" →
           |-> acol};
16
17
       -- Checklist
18
       -- Flight Deck... (can't check)
19
       fuel_chkl: ChecklistItem = mk_ChecklistItem("Fuel_Pump", <SWITCH>,→
            <ON>, false);
20
       pax_sign_chkl: ChecklistItem = mk_ChecklistItem("Passenger_Signs",→
            <SWITCH>, <ON>, false);
21
       windows_chkl: ChecklistItem = mk_ChecklistItem("Windows", <SWITCH-
           >, <ON>, false);
22
       -- Preflight steps
23
       acol_chkl: ChecklistItem = mk_ChecklistItem("Anti⊔Collision⊔Lights→
           ", <SWITCH>, <ON>, false);
24
25
       before_start_procedure: Procedure = [fuel_chkl, pax_sign_chkl, →
           windows_chkl, acol_chkl];
26
27
       aircraft = mk_Aircraft(aircraft_panels, before_start_procedure);
28 types
29
       --@doc The dataref name in X-Plane
30
       Dataref = seq1 of char;
31
32
       -- Aircraft
```

```
33
34
       -- Switches
35
        --Odoc The state a switch can be in
36
       SwitchState = <OFF> | <MIDDLE> | <ON>;
37
38
            -- CLF why have a type kist as a rename?
       ItemState = SwitchState; --@TODO | Button | ...
39
40
       --@doc A switch, with the possible states it can be in, and the \rightarrow
41
           state that it is in
       Switch ::
42
43
            position : SwitchState
44
            middlePosition : bool
45
            inv s ==
46
                (s.position = <MIDDLE> => s.middlePosition);
47
       -- Knob
48
49
       Knob ::
50
            position : nat
51
            --@LF how can a state be an int? perhaps a proper type (i..e. \rightarrow
               subset of int range or a union?)
52
            states : set1 of nat
53
            inv k ==
54
                k.position in set k.states;
55
56
       Lever = nat
57
            inv t == t <= 100;
58
59
       Throttle ::
60
            thrust: Lever
61
            reverser: Lever
62
            inv t ==
63
                (t.reverser > 0 <=> t.thrust = 0);
64
       --@doc The type that the action of the button is
65
66
       ItemType = <SWITCH> | <KNOB> | <BUTTON> | <THROTTLE>;
67
68
        --@doc The unique switch/knob/etc of that aircraft
69
       ObjectType = Switch | Knob | Throttle;
70
        ItemObject ::
            type : ItemType
71
72
            object : ObjectType
73
            inv mk_ItemObject(type, object) ==
74
                     cases type:
75
                             <SWITCH> -> is_Switch(object),
76
                                     -> is_Knob(object),
                             <KNOB>
77
                             <THROTTLE>-> is_Throttle(object),
78
                              --<BUTTON> -> true
79
                             others -> true
80
                     end;
81
82
        --@doc Contains each ItemObject in the Aircraft, e.g. Fuel Pump \rightarrow
           switch
83
       Items = map Dataref to ItemObject;
84
        --@doc Contains the panels (all the items in the aircraft) and the \rightarrow
85
            procedure
86
       Aircraft ::
```

```
87
             items : Items
 88
             procedure : Procedure
 89
             inv mk_Aircraft(i, p) ==
90
             ({ x.procedure | x in seq p } subset dom i);
91
92
         -- Checklist
93
94
         --@doc Item of a checklist, e.g. Landing gear down
95
         ChecklistItem ::
96
             -- @LF again, empty string here doesn't make sense.
97
             procedure : Dataref
98
             type : ItemType
99
             --TODO Check is not only SwitchState
100
             check : SwitchState
101
             checked : bool;
102
103
         --@doc This is an item in the aircraft that complements the item \rightarrow
             in the procedure
104
         ItemAndChecklistItem ::
105
             item : ItemObject
106
             checklistItem: ChecklistItem
107
             inv i == i.item.type = i.checklistItem.type;
108
109
         --@doc A section of a checklist, e.g. Landing Checklist
110
         --@LF shouldn't this be non-empty? What's the point to map a \rightarrow
             checklist name to an empty procedure? Yes.
111
         Procedure = seq1 of ChecklistItem
112
             inv p ==
113
                  --@LF the "trick" for "false not in set S" is neat. It \rightarrow
                     forces a full evaluation, rather than short circuited \rightarrow
                      (i.e. stops at first false).
114
                        I presume this was intended.
                  _ _
115
                  false not in set {
116
                      let first = p(x-1).checked, second = p(x).checked in
117
                               --@LF boolean values don't need equality check
118
                           second => first--((first = true) and (second = \rightarrow
                              false))
119
                      | x in set {2,...,len p}};
120
121 functions
122
         -- PROCEDURES
123
         --@doc Finds the index of the next item in the procedure that \rightarrow
            needs to be completed
124
         procedure_next_item_index: Procedure -> nat1
125
         procedure_next_item_index(p) ==
126
             hd [ x | x in set \{1, \ldots, \text{len } p\} & not p(x).checked ]--p(x).
                 checked = false]
127
         pre
128
              -- Checks procedure has not already been completed
129
             not procedure_completed(p) -- procedure_completed(p) = false
130
         post
131
              -- Checks that the index of the item is the next one to be \rightarrow
                 completed
132
             --@LF your def is quite confusing (to me)
133
             --@LF how do you know that RESULT in inds p? Well, the \rightarrow
                 definition above okay.
134
                    but you can't know whether p(\text{RESULT}-1) will! What if \rightarrow
                 RESULT=1? p(RESULT-1)=p(0) which is invalid!
```

```
135
             (not p(RESULT).checked)
136
             and
137
             (RESULT > 1 => p(RESULT-1).checked)
             --p(RESULT).checked = false
138
139
             --and if RESULT > 1 then
140
             -- p(RESULT-1).checked = true
141
             --else
142
             -- true
143
             ;
144
145
         -- -- @doc Checks if all the procedures have been completed
146
        -- check_all_proc_completed: Checklist -> bool
147
        -- check_all_proc_completed(c) ==
148
               false not in set { procedure_completed(c(x)) | x in set \rightarrow
        ___
            {1,...,len c} };
149
        -- -- @doc Gives the index for the next procedure to complete
150
151
        -- next procedure: Checklist -> nat1
152
        -- next_procedure(c) ==
153
        -- hd [ x | x in set {1,...,len c} & not procedure_completed(c→
           (x))]
154
         -- post
155
        _ _
                RESULT <= len c;
156
157
        --@doc Checks if the procedure has been completed
158
        procedure_completed: Procedure -> bool
159
        procedure_completed(p) ==
160
             false not in set { p(x).checked | x in set {1,...,len p} };
161
162
        --@doc Checks if the next item in the procedure has been completed
163
        check_proc_item_complete: Procedure * Aircraft -> bool
164
         check_proc_item_complete(p, a) ==
165
             --@LF here you have a nice lemma to prove: \rightarrow
                procedure_next_item_index(p) in set inds p!
166
                      I think that's always true
             _ _
167
             let procItem = p(procedure_next_item_index(p)),
168
                     --@LF here you can't tell whether this will be true? i→
                         .e. procItem.procedure in set dom a.items?
169
                 item = a.items(procItem.procedure) in
170
171
                 --TODO need to be able to check for different types of \rightarrow
                    Items
172
                 procItem.check = item.object.position
173
        pre
174
             procedure_completed(p) = false
             --@LF perhaps add
175
176
             --and
177
             --p(procedure_next_item_index(p)).procedure in set dom a.items→
                ?
178
             ;
179
180
        --Odoc Marks next item in procedure as complete
181
        mark_proc_item_complete: Procedure -> Procedure
182
        mark_proc_item_complete(p) ==
183
             let i = procedure_next_item_index(p), item = p(i) in
184
                 p ++ {i |-> complete_item(item)}
            pre
185
186
                 procedure_completed(p) = false;
```

```
188
         --@doc Completes an item in the procedure
        do_proc_item: ItemObject * ChecklistItem -> ItemAndChecklistItem
189
190
        do_proc_item(i, p) ==
191
             let objective = p.check,
192
                 checkckItem = complete_item(p) in
                 -- Checks if the item is in the objective desired by the \rightarrow
193
                     checklist
194
                 if check_item_in_position(i, objective) then
195
                     mk_ItemAndChecklistItem(i, checkckItem)
196
                 else
197
                     mk_ItemAndChecklistItem(move_item(i, p.check), →
                         checkckItem)
198
        pre
199
             p.checked = false
200
        post
201
             -- Checks the item has been moved correctly
202
             check_item_in_position(RESULT.item, p.check);
203
204
        --@doc Completes a procedure step by step
205
        -- a = Aircraft
        complete_procedure: Aircraft -> Aircraft
206
207
        complete_procedure(a) ==
208
             let procedure = a.procedure in
209
                 mk_Aircraft(
210
                     a.items ++ { x.procedure |-> do_proc_item(a.items(x.→
                         procedure), x).item | x in seq procedure },
211
                     [ complete_item(x) | x in seq procedure ]
212
                 )
213
        pre
214
             not procedure_completed(a.procedure)
215
        post
216
             procedure_completed(RESULT.procedure);
217
218
        -- AIRCRAFT ITEMS
219
        --@doc Marks ChecklistItem as complete
220
        complete_item: ChecklistItem -> ChecklistItem
221
        complete_item(i) ==
222
             mk_ChecklistItem(i.procedure, i.type, i.check, true)
223
        pre
224
             i.checked = false;
225
226
        --@doc Moves any type of Item
227
        move_item: ItemObject * ItemState -> ItemObject
228
        move_item(i, s) ==
229
             -- if is_Switch(i) then (implement later)
230
                 let switch: Switch = i.object in
231
                     if check_switch_onoff(switch) and (s <> <MIDDLE>) and \rightarrow
                         switch.middlePosition then
232
                          mk_ItemObject(i.type, move_switch(move_switch()
                             switch, <MIDDLE>), s))
233
                     else
234
                          mk_ItemObject(i.type, move_switch(switch, s))
235
        pre
236
             wf_item_itemstate(i, s)
237
             and not check_item_in_position(i, s);
238
             -- and wf_switch_move(i.object, s);
239
```

187

```
240
         --@doc Moves a specific switch in the aircraft
241
        move switch: Switch * SwitchState -> Switch
242
        move_switch(i, s) ==
243
             mk_Switch(s, i.middlePosition)
244
        pre
245
             wf_switch_move(i, s)
246
        post
247
             RESULT.position = s;
248
249
         --@doc Checks if the switch is in the on or off position
250
        check_switch_onoff: Switch -> bool
251
         check_switch_onoff(s) ==
252
             let position = s.position in
253
                 position = <OFF> or position = <ON>
254
        post
255
             -- Only one can be true at a time
             -- If the switch is in the middle position, then RESULT cannot→
256
                 be true
257
             -- If the switch is in the on/off position, then the RESULT \rightarrow
                will be true
258
             (s.position = <MIDDLE>) <> RESULT;
259
260
         --@doc Checks if the item is already in position for the desired \rightarrow
            state for that item
261
         check_item_in_position: ItemObject * ItemState -> bool
262
         check_item_in_position(i, s) ==
263
             -- if is_Switch(i) then (implement later)
264
                 i.object.position = s
265
        pre
266
             wf_item_itemstate(i,s);
267
268
         --@doc Checks if the Item.object is the same type for the \rightarrow
            ItemState
269
        wf_item_itemstate: ItemObject * ItemState -> bool
270
        wf_item_itemstate(i, s) ==
271
             (is_Switch(i.object) and is_SwitchState(s) and i.type = <→
                SWITCH>)
272
             --TODO check that the item has not already been completed \rightarrow
                before moving item
273
             --TODO add other types of Items
274
             ;
275
276
         --@doc Checks if the move of the Switch is a valid
277
        wf_switch_move: Switch * SwitchState -> bool
278
         wf_switch_move(i, s) ==
279
             -- Checks that the switch not already in the desired state
280
             i.position <> s and
281
             -- The switch has to move one at a time
282
             -- Reasoning for this is that some switches cannot be moved in \rightarrow
                 one quick move
283
             if i.middlePosition = true then
284
                 -- Checks moving the switch away from the middle position
285
                 (i.position = <MIDDLE> and s <> <MIDDLE>)
286
                 -- Checks moving the siwtch to the middle position
287
                 <> (check_switch_onoff(i) = true and s = <MIDDLE>)
288
             else
289
                 check_switch_onoff(i) and s <> <MIDDLE>;
290
```

```
291
292 end Checklist
293
294 /*
295 //@LF always a good idea to run "qc" on your model. Here is its output→
        . PO 21 and 22 show a problem.
296
    //@LF silly me, this was my encoding with the cases missing one \rightarrow
        pattern :-). I can see yours has no issues. Good.
297
298 > qc
299 PO #1, PROVABLE by finite types in 0.002s
300 PO #2, PROVABLE by finite types in 0.0s
301 PO #3, PROVABLE by finite types in 0.0s
302 PO #4, PROVABLE by finite types in 0.0s
303 PO #5, PROVABLE by finite types in 0.0s
304 PO #6, PROVABLE by finite types in 0.0s
305 PO #7, PROVABLE by finite types in 0.0s
306 PO #8, PROVABLE by finite types in 0.0s
307 PO #9, PROVABLE by finite types in 0.001s
308 PO #10, PROVABLE by finite types in 0.001s
309 PO #11, PROVABLE by direct (body is total) in 0.003s
310 PO #12, PROVABLE by witness s = mk_Switch(<MIDDLE>, true) in 0.001s
311 PO #13, PROVABLE by direct (body is total) in 0.001s
312 PO #14, PROVABLE by witness k = mk_Knob(1, [-2]) in 0.0s
313 PO #15, PROVABLE by direct (body is total) in 0.0s
314~ PO #16, PROVABLE by witness t = 0 in 0.0s
315~ PO #17, PROVABLE by direct (body is total) in 0.001s
316 PO #18, PROVABLE by witness t = mk_Throttle(0, 0) in 0.001s
317 PO #19, PROVABLE by direct (body is total) in 0.002s
318 PO #20, PROVABLE by witness i = mk_ItemObject(<KNOB>, mk_Knob(1, [-1])→
        ) in 0.002s
319 PO #21, FAILED in 0.002s: Counterexample: type = \langle BUTTON \rangle, object = \rightarrow
        mk Knob(1, [-1])
320
   Causes Error 4004: No cases apply for <BUTTON> in 'Checklist' (formal/→
        checklist.vdmsl) at line 119:13
    ____
321
322 ItemObject':⊔total⊔function⊔obligation⊔in⊔'Checklist'⊔(formal/→
        checklist.vdmsl)_at_line_118:13
323 (forall_mk_ItemObject'(type, object):ItemObject'!u&
324 ____is_(inv_ItemObject'(mk_ItemObject'!(type,_object)),_bool))
325
326 PO_#22,_FAILED_by_direct_in_0.005s:_Counterexample:_type_=<BUTTON>
327 PO_#23,_PROVABLE_by_witness_type_=<KNOB>,_object_=mk_Knob(1,_[-1])_→
        in_{\sqcup}0.002s
328 POu#24, PROVABLE by direct (body is total) in 0.001s
329 PO_#25, PROVABLE_by_witness_i__mk_ItemAndChecklistItem(mk_ItemObject→
        (<KNOB>, umk_Knob(1, [-1])), umk_ChecklistItem([], u<KNOB>, u<MIDDLE>, →
        \Boxtrue))\Boxin\Box0.001s
330 PO<sub>U</sub>#26, <u>MAYBE</u> in 0.003s
331 \text{ PO}_{\sqcup}#27,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.003s
332 PO<sub>U</sub>#28, <u>MAYBE</u>in<sub>U</sub>0.002s
333 PO_#29, PROVABLE_by_witness_p_=[mk_ChecklistItem([], <BUTTON>, <+
        MIDDLE>, utrue)] uinu0.001s
334 PO<sub>U</sub>#30, <u>MAYBE</u> in 0.002s
335 PO<sub>U</sub>#31, <u>MAYBE</u>in<sub>U</sub>0.001s
336 PO<sub>U</sub>#32, <u>MAYBE</u> in 0.003s
337 PO_{\sqcup}#33,\_MAYBE_{\sqcup}in_{\sqcup}0.002s
338 PO<sub>U</sub>#34, <u>MAYBE</u>in<sub>U</sub>0.001s
```

```
339
      POu#35, MAYBEuinu0.002s
340
      PO<sub>11</sub>#36, MAYBE11in10.009s
      POu#37, MAYBEuinu0.008s
341
342 PO<sub>U</sub>#38, <u>MAYBE</u><sub>U</sub>in<sub>U</sub>0.007s
343 PO<sub>U</sub>#39, <u>MAYBE</u> 10.009s
344 PO<sub>U</sub>#40, <u>MAYBE</u> <u>in</u> 0.002s
345 \quad PO_{\sqcup}#41, \_MAYBE_{\sqcup}in_{\sqcup}0.001s
      POu#42, MAYBEuinu0.001s
346
347
      PO<sub>U</sub>#43, MAYBE<sub>U</sub>in<sub>U</sub>0.002s
      POu#44, MAYBEuinu0.002s
348
349
      POu#45, MAYBEuinu0.003s
      POu#46, MAYBEuinu0.002s
350
351
      POu#47, MAYBEuinu0.002s
352 PO<sub>U</sub>#48, <u>MAYBE</u> in 0.001s
353 PO_{\sqcup}#49,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
354 PO<sub>U</sub>#50,<sub>U</sub>MAYBE<sub>U</sub>in<sub>U</sub>0.0s
355 PO<sub>11</sub>#51, MAYBE11in10.0s
356 PO<sub>11</sub>#52, MAYBE<sub>11</sub>in<sub>11</sub>0.005s
357 POu#53,uPROVABLEubyutrivialupuinusetu(domuchecklist)uinu0.001s
358 POu#54, MAYBEuinu0.006s
359 PO<sub>11</sub>#55, MAYBE11in10.0s
360 \text{ PO}_{\sqcup}#56, \_MAYBE_{\sqcup}in_{\sqcup}0.001s
361
      POu#57, MAYBEuinu0.001s
362
      PO<sub>□</sub>#58, <sub>□</sub>MAYBE<sub>□</sub>in<sub>□</sub>0.001s
363
      PO<sub>□</sub>#59,<sub>□</sub>MAYBE<sub>□</sub>in<sub>□</sub>0.001s
364
      POu#60, MAYBEuinu0.001s
365 PO<sub>U</sub>#61, MAYBE<sub>U</sub>in<sub>U</sub>0.001s
366 POu#62, MAYBEuinu0.0s
367
      POu#63, PROVABLE by finite types in 0.001s
368 POu#64, PROVABLE by finite types in 0.001s
369 PO_{\sqcup}#65,_{\sqcup}PROVABLE_{\sqcup}by_{\sqcup}finite_{\sqcup}types_{\sqcup}in_{\sqcup}0.001s
370 PO<sub>U</sub>#66, MAYBE<sub>U</sub>in<sub>U</sub>0.001s
371 >
372 */
```

## Appendix B

# Database

## B.1 SQL Schemas

```
CREATE TABLE IF NOT EXISTS Project (
1
        id INTEGER PRIMARY KEY AUTOINCREMENT NOT NULL,
^{2}
        name TEXT NOT NULL,
3
        aircraftType TEXT NOT NULL,
^{4}
        createdUTC TEXT NOT NULL,
\mathbf{5}
        modifiedUTC TEXT
6
   );
7
8
   createProject:
9
  INSERT INTO Project(name, aircraftType, createdUTC)
10
  VALUES (?, ?, ?);
11
^{12}
   selectAllProjects:
13
   SELECT * FROM Project;
14
15
<sup>16</sup> selectProjectById:
17 SELECT * FROM Project
18 WHERE id = ?;
19
20 countProjects:
21 SELECT COUNT(*) FROM Project;
```

Listing B.2: SQL Schema for Project

```
CREATE TABLE IF NOT EXISTS Procedure (
 1
        id INTEGER PRIMARY KEY AUTOINCREMENT NOT NULL,
\mathbf{2}
        projectId INTEGER NOT NULL,
3
        name TEXT NOT NULL,
4
        type TEXT NOT NULL,
\mathbf{5}
        description TEXT NOT NULL,
6
        createdUTC TEXT NOT NULL,
7
        modifiedUTC TEXT,
8
        FOREIGN KEY (projectId) REFERENCES Project(id)
9
   );
10
11
   createProcedure:
12
   INSERT INTO Procedure(projectId, name, type, description, createdUTC)
13
    VALUES (?, ?, ?, ?, ?);
^{14}
15
   selectProcedures:
16
   SELECT * FROM Procedure
17
   WHERE projectId = ?;
18
19
   selectProcedureById:
20
   SELECT * FROM Procedure
^{21}
   WHERE id = ?;
^{22}
23
  countProcedures:
^{24}
   SELECT COUNT(*) FROM Procedure
^{25}
   WHERE projectId = ?;
26
```

Listing B.3: SQL Schema for Procedure

```
CREATE TABLE IF NOT EXISTS Action (
1
        id INTEGER PRIMARY KEY AUTOINCREMENT NOT NULL,
2
        procedureId INTEGER NOT NULL,
3
        step INTEGER NOT NULL,
4
        type TEXT NOT NULL,
\mathbf{5}
        goal TEXT NOT NULL,
6
        FOREIGN KEY (procedureId) REFERENCES Procedure(id)
7
   );
8
9
   createAction:
10
   INSERT INTO Action(procedureId, step, type, goal)
11
   VALUES (?, ?, ?, ?);
12
13
   selectActions:
14
   SELECT * FROM Action
15
   WHERE procedureId = ?;
16
17
   countActions:
18
   SELECT COUNT(*) FROM Action
19
   WHERE procedureId = ?;
20
21
  deleteByProcedure:
22
   DELETE FROM Action
^{23}
^{24}
   WHERE procedureId = ?;
```

Listing B.4: SQL Schema for Action

```
CREATE TABLE IF NOT EXISTS Test (
1
       id INTEGER PRIMARY KEY AUTOINCREMENT NOT NULL,
2
       procedureId INTEGER NOT NULL,
3
4
       startUTC TEXT NOT NULL,
       endUTC TEXT,
5
       FOREIGN KEY (procedureId) REFERENCES Procedure(id)
6
   );
7
8
   startTest:
9
   INSERT INTO Test(procedureId, startUTC)
10
   VALUES (?, ?);
11
12
   endTest:
13
   UPDATE Test
14
  SET endUTC = ?
15
   WHERE id = ?;
16
17
   lastInsertedRowId:
18
   SELECT last_insert_rowid();
19
```

Listing B.5: SQL Schema for Test

```
CREATE TABLE IF NOT EXISTS ActionResult (
1
2
        id INTEGER PRIMARY KEY AUTOINCREMENT NOT NULL,
        testId INTEGER NOT NULL,
3
        actionId INTEGER NOT NULL,
4
        initState TEXT NOT NULL,
\mathbf{5}
        endState TEXT,
6
        startUTC TEXT NOT NULL,
7
        endUTC TEXT,
8
        FOREIGN KEY (testId) REFERENCES Test(id),
9
        FOREIGN KEY (actionId) REFERENCES Action(id)
10
   );
11
^{12}
   startResult:
^{13}
   INSERT INTO ActionResult(testId, actionId, initState, startUTC)
14
   VALUES (?, ?, ?, ?);
15
16
  finishResult:
17
   UPDATE ActionResult
18
   SET endState = ?, endUTC = ?
19
   WHERE id = ?;
20
^{21}
   lastInsertedRowId:
22
   SELECT last_insert_rowid();
23
```

Listing B.6: SQL Schema for ActionResult

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