Testing Quick Reference Handbooks in Flight Simulators

Anthony Berg (200871682)
Supervisor: Dr Leo Freitas

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Preface

Abstract

This is an abstract.

Declaration

I declare that this dissertation represents my own work except where otherwise stated.

Acknowledgements

I would like to thank my supervisor Leo Freitas for supporting, guiding, and providing with areas of improvement for me throughout the project.

Contents

Chapter 1

Introduction

1.1 Scene

- Designing Emergency Checklists is difficult
- Procedures in checklists must be tested in simulators [1], which usually means trained pilots test it, as the tests need to work consistently [2] (making sure it's not lengthy, concise and gets critical procedures)
- Checklists are usually carried out in high workload environments, especially emergency ones

1.2 Motivation

- Testing procedures in checklists are often neglected [1]
- There are some checklists that may not be fit for certain scenarios - e.g. ditching (water landing) checklist for US Airways Flight 1549 assumed at least one engine was running [3], but in this scenario, there were none
- Some checklists may make pilots 'stuck' - not widely implemented, could be fixed with 'opt out' points. e.g. US Airways 1549, plane below 3000ft, could have skip to later in the checklist to something like turn on APU, otherwise plane will have limited control [3].
- Checklists may take too long to carry out - Swissair 111

1.3 Aim

The goal of this project is to test checklists in Quick Reference Handbooks (QRH) for flaws that could compromise the aircraft and making sure that the tests can be completed in a reasonable amount of time by pilots. It is also crucial to make sure that the tests are reproducible in the same flight conditions and a variety of flight conditions.

1.4 Objectives

1. Research current checklists that may be problematic and are testable in the QRH tester being made
2. Implement a formal model that runs through checklists, with the research gathered to produce an accurate test
   (a) Understand the relative states of the aircraft that need to be captured
   (b) Ensure that the results of the checklist procedures are consistent
3. Implement a QRH tester manager that
   - Runs the formal model and reacts to the output of the formal model

- Connect to a flight simulator to run actions from the formal model
- Implement checklist procedures to be tested, run them, and get feedback on how well the procedure ran

Chapter 2

Background

2.1 Hypothesis

- Checklists can be tested in a simulated environment to find flaws in checklist for things like
  - Can be done in an amount of time that will not endanger aircraft
  - Provides reproducible results
  - Procedures will not endanger aircraft or crew further (Crew referring to Checklist Manifesto with the cargo door blowout)
- Results in being able to see where to improve checklists

2.2 Safety in Aviation

2.2.1 History

- 70-80% of aviation accidents are attributed to human factors [4]

2.2.2 Checklists

- Checklists have been shown to aid in minimising human errors [2]
- However, checklists can be misleading and compromise the safety of the aircraft due to them being either too confusing or taking too long to complete [1]
- That is why testing checklists are important to avoid these situations

2.3 Formal Methods

2.3.1 History

2.3.2 Application

2.4 Solution Stack

- There would be around 3 main components to this tester
  - Formal Model
  - Flight Simulator plugin
  - Checklist Tester (to connect the formal model and flight simulator)
- As VDM-SL is being used, it uses VDMJ to parse the model [5]. This was a starting point for the tech stack, as VDMJ is also open source.
- VDMJ is written in Java [5], therefore to simplify implementing VDMJ into the Checklist Tester, it would be logical to use a Java virtual machine (JVM) language.

2.4.1 Formal Model

- There were a few ways of implementing the formal model into another application
- Some of these methods were provided by Overture [6]
  - RemoteControl interface
  - VDMTools API [7]
- However, both of these methods did not suit what was required as most of the documentation for RemoteControl was designed for the Overture Tool IDE. VDMTools may have handled the formal model differently
- The choice was to create a VDMJ wrapper, as the modules are available on Maven

2.4.2 Checklist Tester

JVM Language

- There are multiple languages that are made for or support JVMs [8]
- Requirements for language
  - Be able to interact with Java code because of VDMJ
  - Have Graphical User Interface (GUI) libraries
  - Have good support (the more popular, the more resources available)
- The main contenders were Java and Kotlin [9]
- Kotlin [9] was the choice in the end as Google has been putting Kotlin first instead of Java. Kotlin also requires less boilerplate code (e.g. getters and setters) [10]

Graphical User Interface

- As the tester is going to include a UI, the language choice was still important
- There are a variety of GUI libraries to consider using
  - JavaFX [11]
  - Swing [12]
  - Compose Multiplatform [13]
- The decision was to use Compose Multiplatform in the end, due to time limitations and having prior experience in using Flutter [14]
- Compose Multiplatform has the ability to create a desktop application and a server, which would allow for leeway if a server would be needed

2.4.3 Flight Simulator Plugin

- There are two main choices for flight simulators that can be used for professional simulation
  - X-Plane [15]
  - Prepar3D [16]
- X-Plane was the choice due to having better documentation for the SDK, and a variety of development libraries for the simulator itself
- For the plugin itself, there was already a solution developed by NASA, X-Plane Connect [17] that is more appropriate due to the time limitations and would be more likely to be reliable as it has been developed since 2015

Chapter 3

Design/Implementation

3.1 Components

Splitting up the project into multiple components has been useful for

- Aiding in planning to make the implementation more efficient
- Delegating specific work tasks
- Making the project modular, for example, allowing for a different simulator to be implemented with minimal need to refactor other parts of the codebase

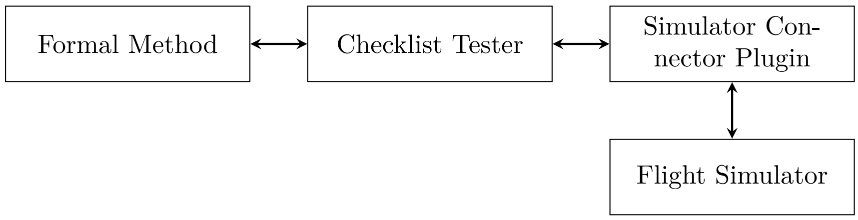

Figure 3.1: Abstract layout of components

Each of the components in Figure 3.1 will be covered in detail in this chapter.

3.2 Formal Method

- Formal modelling is the heart of the logic for testing checklists
- Formal model created using VDM-SL
- It allows to test that the checklists have been completed in a proper manner - and that it is provable
- Model keeps track of
  - Aircraft state
  - Checklist state
- If an error were to occur in the model, this can be relayed that there was something wrong with running the test for the checklist, such as:
  - Procedure compromises integrity of aircraft
  - There is not enough time to complete the procedure
  - There is a contradiction with the steps of the checklist

3.3 Checklist Tester

Brief overview of what it is supposed to do...

3.3.1 Designing

- Used Figma to create a design for the application
- Allows for implementing the front end to be faster because:
  - They act as a requirement for code
  - You do not forget what needs to be implemented
  - Keeps everything consistent
  - Allows to think about making parts of the GUI modular and what components can be reused
- Figma allows for plugins such as Material 3 colours and Material 3 components
- Figure 3.2 is the final design that will be used for the program

Limitations of Figma

- The Material 3 Components in Figma do not include features that are available in Jetpack Compose
- In this project, the 'Simulator Test' at the bottom of Figure 3.2 does not include a leading icon [18], and therefore had to be a trailing checkbox
- This was overcome by adding comments in Figma as a reminder of how the actual implementation should be like
- Another limitation is that in Figure 3.2, the title of the screen in the top app bar [19] is not centered, and that is because the auto layout feature in Figma allows for equal spacing, rather than having each in a set position

3.3.2 Compose Multiplatform

Setup

- Used the *Kotlin Multiplatform Wizard* to create projects as it allows for runtime environments to be specified (in this case, Desktop and Server)
- Provides necessary build configurations in Gradle
- Planning what to implement important as Compose is designed to use modular components, otherwise a nested mess would happen, code harder to read. Figure 3.3 shows example of using modular code from the Actions screen in project (with code omissions)
- Used Voyager [20] to handle screens
- Used Koin [21] for dependency injection, to be able to get data from the database and VDMJ
  - Chose to use it because of Voyager integration with Koin [22]
  - Required as the application will be unresponsive when making requests to the database and/or VDMJ
  - Used asynchronous coroutines to prevent the program from being blocked

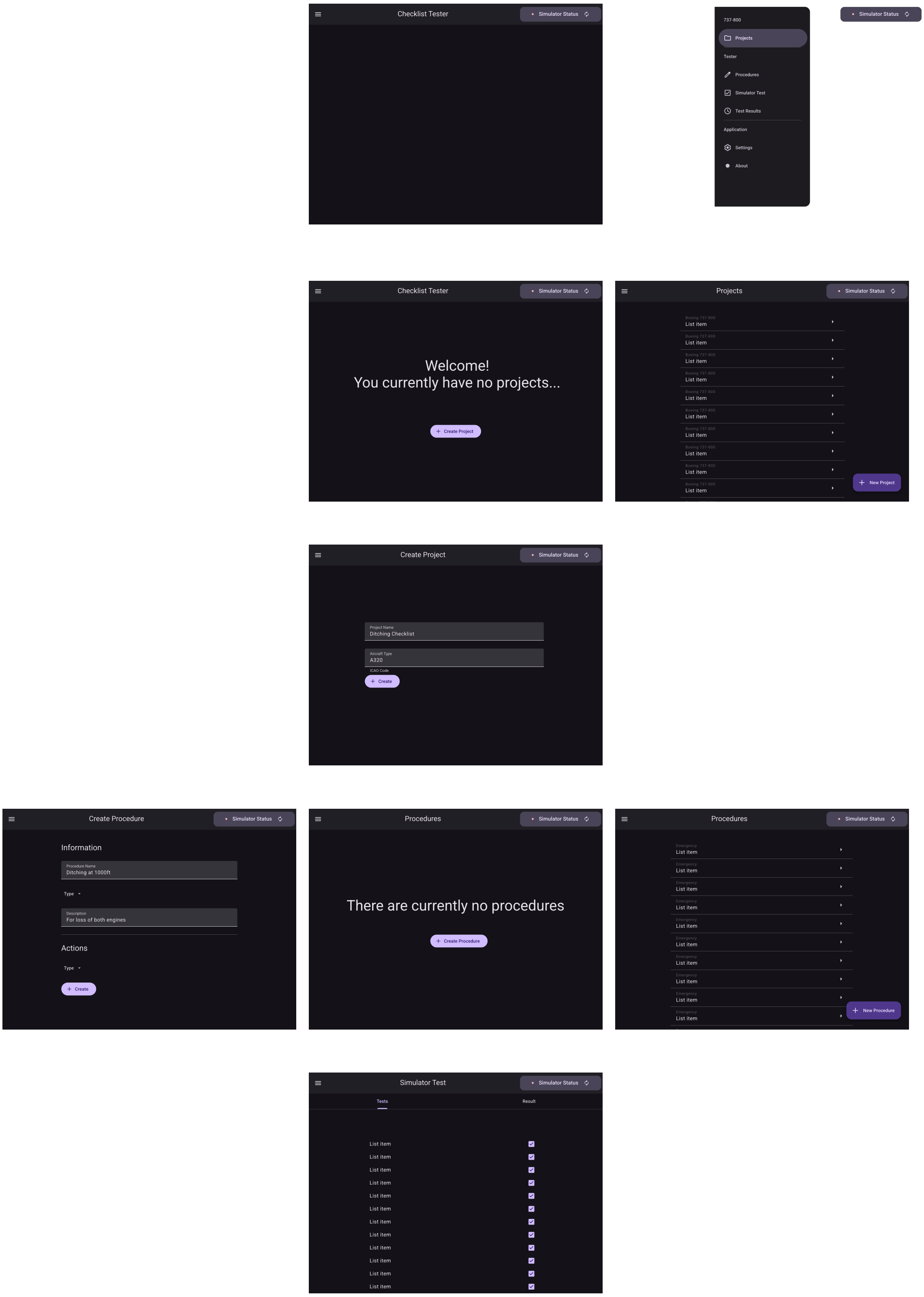

Figure 3.2: Design for the Checklist Connector GUI in Figma

```kotlin
@Composable
override fun Content() {
    // Content variables...

    Scaffold(
        topBar = {/* Composable content... */},
    ) {
        Column(/* Column option parameters... */) {
            Box(/* Box option parameters... */) {
                LazyColumn(/* LazyColumn option parameters... */) {

                    item {
                        Header()
                    }

                    items(
                        items = inputs,
                        key = { input -> input.id }
                    ) { item ->
                        ActionItem(item)
                    }
                }
            }
        }
    }
}

@Composable
private fun Header() {
    Text(text = "Edit Actions")
}

@Composable
private fun ActionItem(item: Action) {
    Column (/* Column option parameters... */) {
        Row(/* Row option parameters... */) {
            Text(text = "Action ${item.step + 1}")

            IconButton(/* IconButton definition parameters... */) {
                Icon(
                    Icons.Outlined.Delete,
                    // Rest of Icon options...
                )
            }
        }

        Row(/* Row option parameters... */) {
            OutlinedTextField(/* TextField definition parameters... */)

            OutlinedTextField(/* TextField definition parameters... */)
        }

        HorizontalDivider()
    }
}
```

Figure 3.3: Example of modular code in Compose

3.3.3 Storing Data

3.3.4 VDMJ Wrapper

3.3.5 Connecting to the Flight Simulator

3.3.6 Testing

3.4 Simulator Connector Plugin

3.4.1 Creating Maven Package

- XPC package is not published on a public Maven repository
- There has been a pull request that was merged to the *develop* branch that provides Maven POMs [23]. However, the maintainer for the project, at the time, did not have enough time to figure out the process of publishing the package to a Maven repository [24]
- Therefore, had to find an alternative way to implement
- Jitpack [25]
  - In theory, simple to publish a repository, all that is required is a GitHub repository and searching if one has already been created on JitPack or build and publish a specific version
  - However, due to the structure of the XPC repository, JitPack could not locate the build tools (Apache Maven in this case) as JitPack only searches on the root directory for the compatible build tools
- Gradle gitRepository [26]
  - There was not a lot of documentation
  - Ambiguous on how to define directory for where the Java library is located in the Git repository
  - However, as XPC was only built with Maven, Gradle was not able add the dependency as `gitRepository()` only works with Gradle builds [27]
- Resorted to using a compiled Jar file and adding the dependency to Gradle
- Not happy about that because it means maintaining it will be more difficult as it is not as simple as just changing the version number
- Later, resorted to adding Gradle build files to XPC
- Used automatic conversion from Maven to Gradle using `gradle init` command [28]
- Had to add local dependencies due to how Gradle works differently
- Had to fix previous structure of Maven POM as the grouping as not good

3.4.2 Submitting a Pull Request

3.5 Scenarios

- Use a Quick Reference Handbook (QRH) to find potential list of checklists to test
- Look at previous accident reports that had an incident related to checklists and test it with my tool to see if it will pick it up
- These previous accident reports can be good metrics to know what statistics to look out for

3.6 Decisions

Chapter 4

Results

4.1 Problems Found

4.2 LOC?

4.3 Reflection

4.4 Time Spent

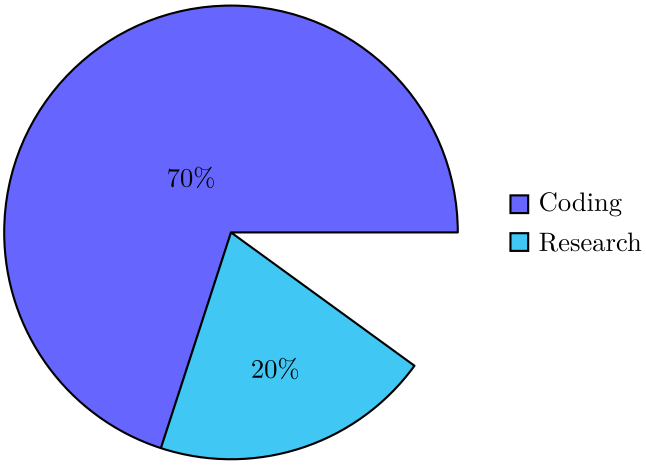

Figure 4.1: Time spent on sections of project

Chapter 5

Conclusion

5.1 Changes

5.2 Objectives

5.3 What Next

Appendix A

Formal Model

```
module Checklist
exports all
definitions

values
    -- Before Start Checklist
    -- Items in Aircraft
    -- Flight Deck... (can't check)
    fuel: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, false));
    pax_sign: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, true));
    windows: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<ON>, false));
    -- Preflight steps
    acol: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, false));

    aircraft_panels: Items = {"Fuel Pump" |-> fuel, "Passenger Signs" |-> pax_sign, "Windows" |-> windows, "Anti Collision Lights" |-> acol};

    -- Checklist
    -- Flight Deck... (can't check)
    fuel_chkl: ChecklistItem = mk_ChecklistItem("Fuel Pump", <SWITCH>, <ON>, false);
    pax_sign_chkl: ChecklistItem = mk_ChecklistItem("Passenger Signs", <SWITCH>, <ON>, false);
    windows_chkl: ChecklistItem = mk_ChecklistItem("Windows", <SWITCH>, <ON>, false);
    -- Preflight steps
    acol_chkl: ChecklistItem = mk_ChecklistItem("Anti Collision Lights", <SWITCH>, <ON>, false);

    before_start_procedure: Procedure = [fuel_chkl, pax_sign_chkl, windows_chkl, acol_chkl];

    aircraft = mk_Aircraft(aircraft_panels, before_start_procedure);
types
    --@doc The dataref name in X-Plane
    Dataref = seq1 of char;

    -- Aircraft
```

```

-- Switches
--@doc The state a switch can be in
SwitchState = <OFF> | <MIDDLE> | <ON>;

    --@LF why have a type kist as a rename?
ItemState = SwitchState; --@TODO | Button | ...

--@doc A switch, with the possible states it can be in, and the state that it is in
Switch ::
    position : SwitchState
    middlePosition : bool
    inv s ==
        (s.position = <MIDDLE> => s.middlePosition);

-- Knob
Knob ::
    position : nat
    --@LF how can a state be an int? perhaps a proper type (i..e. subset of int range or a union?)
    states : set1 of nat
    inv k ==
        k.position in set k.states;

Lever = nat
    inv t == t <= 100;

Throttle ::
    thrust: Lever
    reverser: Lever
    inv t ==
        (t.reverser > 0 <=> t.thrust = 0);

--@doc The type that the action of the button is
ItemType = <SWITCH> | <KNOB> | <BUTTON> | <THROTTLE>;

--@doc The unique switch/knob/etc of that aircraft
ObjectType = Switch | Knob | Throttle;
ItemObject ::
    type : ItemType
    object : ObjectType
    inv mk_ItemObject(type, object) ==
            cases type:
                    <SWITCH> -> is_Switch(object),
                    <KNOB>   -> is_Knob(object),
                    <THROTTLE>-> is_Throttle(object),
                    --<BUTTON> -> true
                    others -> true
            end;

--@doc Contains each ItemObject in the Aircraft, e.g. Fuel Pump switch
Items = map Dataref to ItemObject;

--@doc Contains the panels (all the items in the aircraft) and the procedure
Aircraft ::
```

```
        items : Items
        procedure : Procedure
        inv mk_Aircraft(i, p) ==
        ({ x.procedure | x in seq p } subset dom i);

    -- Checklist

    --@doc Item of a checklist, e.g. Landing gear down
    ChecklistItem ::
        --@LF again, empty string here doesn't make sense.
        procedure : Dataref
        type : ItemType
        --TODO Check is not only SwitchState
        check : SwitchState
        checked : bool;

    --@doc This is an item in the aircraft that complements the item in the procedure
    ItemAndChecklistItem ::
        item : ItemObject
        checklistItem: ChecklistItem
        inv i == i.item.type = i.checklistItem.type;

    --@doc A section of a checklist, e.g. Landing Checklist
    --@LF shouldn't this be non-empty? What's the point to map a checklist name to an empty procedure? Yes.
    Procedure = seq1 of ChecklistItem
        inv p ==
            --@LF the "trick" for "false not in set S" is neat. It forces a full evaluation, rather than short circuited (i.e. stops at first false).
            --    I presume this was intended.
            false not in set {
                let first = p(x-1).checked, second = p(x).checked in
                        --@LF boolean values don't need equality check
                    second => first--((first = true) and (second = false))
                | x in set {2,...,len p}};

functions
    -- PROCEDURES
    --@doc Finds the index of the next item in the procedure that needs to be completed
    procedure_next_item_index: Procedure -> nat1
    procedure_next_item_index(p) ==
        hd [ x | x in set {1,...,len p} & not p(x).checked ]--p(x).checked = false]
    pre
        -- Checks procedure has not already been completed
        not procedure_completed(p)--procedure_completed(p) = false
    post
        -- Checks that the index of the item is the next one to be completed
        --@LF your def is quite confusing (to me)
        --@LF how do you know that RESULT in inds p? Well, the definition above okay.
        --    but you can't know whether p(RESULT-1) will! What if RESULT=1? p(RESULT-1)=p(0) which is invalid!
```

```
        (not p(RESULT).checked)
        and
        (RESULT > 1 => p(RESULT-1).checked)
        --p(RESULT).checked = false
        --and if RESULT > 1 then
        --    p(RESULT-1).checked = true
        --else
        --    true
        ;

    -- --@doc Checks if all the procedures have been completed
    -- check_all_proc_completed: Checklist -> bool
    -- check_all_proc_completed(c) ==
    --     false not in set { procedure_completed(c(x)) | x in set {1,...,len c} };

    -- --@doc Gives the index for the next procedure to complete
    -- next_procedure: Checklist -> nat1
    -- next_procedure(c) ==
    --     hd [ x | x in set {1,...,len c} & not procedure_completed(c(x))]
    -- post
    --     RESULT <= len c;

    --@doc Checks if the procedure has been completed
    procedure_completed: Procedure -> bool
    procedure_completed(p) ==
        false not in set { p(x).checked | x in set {1,...,len p} };

    --@doc Checks if the next item in the procedure has been completed
    check_proc_item_complete: Procedure * Aircraft -> bool
    check_proc_item_complete(p, a) ==
        --@LF here you have a nice lemma to prove: procedure_next_item_index(p) in set inds p!
        --        I think that's always true
        let procItem = p(procedure_next_item_index(p)),
                --@LF here you can't tell whether this will be true? i.e. procItem.procedure in set dom a.items?
            item = a.items(procItem.procedure) in

            --TODO need to be able to check for different types of Items
            procItem.check = item.object.position
    pre
        procedure_completed(p) = false
        --@LF perhaps add
        --and
        --p(procedure_next_item_index(p)).procedure in set dom a.items?
        ;

    --@doc Marks next item in procedure as complete
    mark_proc_item_complete: Procedure -> Procedure
    mark_proc_item_complete(p) ==
        let i = procedure_next_item_index(p), item = p(i) in
            p ++ {i |-> complete_item(item)}
        pre
            procedure_completed(p) = false;
```

```

    --@doc Completes an item in the procedure
    do_proc_item: ItemObject * ChecklistItem -> ItemAndChecklistItem
    do_proc_item(i, p) ==
        let objective = p.check,
            checkckItem = complete_item(p) in
            -- Checks if the item is in the objective desired by the checklist
            if check_item_in_position(i, objective) then
                mk_ItemAndChecklistItem(i, checkckItem)
            else
                mk_ItemAndChecklistItem(move_item(i, p.check), checkckItem)
    pre
        p.checked = false
    post
        -- Checks the item has been moved correctly
        check_item_in_position(RESULT.item, p.check);

    --@doc Completes a procedure step by step
    -- a = Aircraft
    complete_procedure: Aircraft -> Aircraft
    complete_procedure(a) ==
        let procedure = a.procedure in
            mk_Aircraft(
                a.items ++ { x.procedure |-> do_proc_item(a.items(x.procedure), x).item | x in seq procedure },
                [ complete_item(x) | x in seq procedure ]
            )
    pre
        not procedure_completed(a.procedure)
    post
        procedure_completed(RESULT.procedure);

    -- AIRCRAFT ITEMS
    --@doc Marks ChecklistItem as complete
    complete_item: ChecklistItem -> ChecklistItem
    complete_item(i) ==
        mk_ChecklistItem(i.procedure, i.type, i.check, true)
    pre
        i.checked = false;

    --@doc Moves any type of Item
    move_item: ItemObject * ItemState -> ItemObject
    move_item(i, s) ==
        -- if is_Switch(i) then (implement later)
            let switch: Switch = i.object in
                if check_switch_onoff(switch) and (s <> <MIDDLE>) and switch.middlePosition then
                    mk_ItemObject(i.type, move_switch(move_switch(switch, <MIDDLE>), s))
                else
                    mk_ItemObject(i.type, move_switch(switch, s))
    pre
        wf_item_itemstate(i, s)
        and not check_item_in_position(i, s);
        -- and wf_switch_move(i.object, s);

```

```
    --@doc Moves a specific switch in the aircraft
    move_switch: Switch * SwitchState -> Switch
    move_switch(i, s) ==
        mk_Switch(s, i.middlePosition)
    pre
        wf_switch_move(i, s)
    post
        RESULT.position = s;

    --@doc Checks if the switch is in the on or off position
    check_switch_onoff: Switch -> bool
    check_switch_onoff(s) ==
        let position = s.position in
            position = <OFF> or position = <ON>
    post
        -- Only one can be true at a time
        -- If the switch is in the middle position, then RESULT cannot be true
        -- If the switch is in the on/off position, then the RESULT will be true
        (s.position = <MIDDLE>) <> RESULT;

    --@doc Checks if the item is already in position for the desired state for that item
    check_item_in_position: ItemObject * ItemState -> bool
    check_item_in_position(i, s) ==
        -- if is_Switch(i) then (implement later)
            i.object.position = s
    pre
        wf_item_itemstate(i,s);

    --@doc Checks if the Item.object is the same type for the ItemState
    wf_item_itemstate: ItemObject * ItemState -> bool
    wf_item_itemstate(i, s) ==
        (is_Switch(i.object) and is_SwitchState(s) and i.type = <SWITCH>)
        --TODO check that the item has not already been completed before moving item
        --TODO add other types of Items
        ;

    --@doc Checks if the move of the Switch is a valid
    wf_switch_move: Switch * SwitchState -> bool
    wf_switch_move(i, s) ==
        -- Checks that the switch not already in the desired state
        i.position <> s and
        -- The switch has to move one at a time
        -- Reasoning for this is that some switches cannot be moved in one quick move
        if i.middlePosition = true then
            -- Checks moving the switch away from the middle position
            (i.position = <MIDDLE> and s <> <MIDDLE>)
            -- Checks moving the siwtch to the middle position
            <> (check_switch_onoff(i) = true and s = <MIDDLE>)
        else
            check_switch_onoff(i) and s <> <MIDDLE>;
```

```

end Checklist

/*
//@LF always a good idea to run "qc" on your model. Here is its output. PO 21 and 22 show a problem.
//@LF silly me, this was my encoding with the cases missing one pattern :-). I can see yours has no issues. Good.

> qc
PO #1, PROVABLE by finite types in 0.002s
PO #2, PROVABLE by finite types in 0.0s
PO #3, PROVABLE by finite types in 0.0s
PO #4, PROVABLE by finite types in 0.0s
PO #5, PROVABLE by finite types in 0.0s
PO #6, PROVABLE by finite types in 0.0s
PO #7, PROVABLE by finite types in 0.0s
PO #8, PROVABLE by finite types in 0.0s
PO #9, PROVABLE by finite types in 0.001s
PO #10, PROVABLE by finite types in 0.001s
PO #11, PROVABLE by direct (body is total) in 0.003s
PO #12, PROVABLE by witness s = mk_Switch(<MIDDLE>, true) in 0.001s
PO #13, PROVABLE by direct (body is total) in 0.001s
PO #14, PROVABLE by witness k = mk_Knob(1, [-2]) in 0.0s
PO #15, PROVABLE by direct (body is total) in 0.0s
PO #16, PROVABLE by witness t = 0 in 0.0s
PO #17, PROVABLE by direct (body is total) in 0.001s
PO #18, PROVABLE by witness t = mk_Throttle(0, 0) in 0.001s
PO #19, PROVABLE by direct (body is total) in 0.002s
PO #20, PROVABLE by witness i = mk_ItemObject(<KNOB>, mk_Knob(1, [-1])) in 0.002s
PO #21, FAILED in 0.002s: Counterexample: type = <BUTTON>, object = mk_Knob(1, [-1])
Causes Error 4004: No cases apply for <BUTTON> in 'Checklist' (formal/checklist.vdmsl) at line 119:13
----
ItemObject':␣total␣function␣obligation␣in␣'Checklist'␣(formal/checklist.vdmsl)␣at␣line␣118:13
(forall␣mk_ItemObject'(type, object):ItemObject'!␣&
␣␣is_(inv_ItemObject'(mk_ItemObject'!(type,␣object)),␣bool))

PO␣#22,␣FAILED␣by␣direct␣in␣0.005s:␣Counterexample:␣type␣=␣<BUTTON>
PO␣#23,␣PROVABLE␣by␣witness␣type␣=␣<KNOB>,␣object␣=␣mk_Knob(1,␣[-1])␣in␣0.002s
PO␣#24,␣PROVABLE␣by␣direct␣(body␣is␣total)␣in␣0.001s
PO␣#25,␣PROVABLE␣by␣witness␣i␣=␣mk_ItemAndChecklistItem(mk_ItemObject(<KNOB>,␣mk_Knob(1,␣[-1])),␣mk_ChecklistItem([],␣<KNOB>,␣<MIDDLE>,␣true))␣in␣0.001s
PO␣#26,␣MAYBE␣in␣0.003s
PO␣#27,␣MAYBE␣in␣0.003s
PO␣#28,␣MAYBE␣in␣0.002s
PO␣#29,␣PROVABLE␣by␣witness␣p␣=␣[mk_ChecklistItem([],␣<BUTTON>,␣<MIDDLE>,␣true)]␣in␣0.001s
PO␣#30,␣MAYBE␣in␣0.002s
PO␣#31,␣MAYBE␣in␣0.001s
PO␣#32,␣MAYBE␣in␣0.003s
PO␣#33,␣MAYBE␣in␣0.002s
PO␣#34,␣MAYBE␣in␣0.001s
```

```
PO␣#35,␣MAYBE␣in␣0.002s
PO␣#36,␣MAYBE␣in␣0.009s
PO␣#37,␣MAYBE␣in␣0.008s
PO␣#38,␣MAYBE␣in␣0.007s
PO␣#39,␣MAYBE␣in␣0.009s
PO␣#40,␣MAYBE␣in␣0.002s
PO␣#41,␣MAYBE␣in␣0.001s
PO␣#42,␣MAYBE␣in␣0.001s
PO␣#43,␣MAYBE␣in␣0.002s
PO␣#44,␣MAYBE␣in␣0.002s
PO␣#45,␣MAYBE␣in␣0.003s
PO␣#46,␣MAYBE␣in␣0.002s
PO␣#47,␣MAYBE␣in␣0.002s
PO␣#48,␣MAYBE␣in␣0.001s
PO␣#49,␣MAYBE␣in␣0.001s
PO␣#50,␣MAYBE␣in␣0.0s
PO␣#51,␣MAYBE␣in␣0.0s
PO␣#52,␣MAYBE␣in␣0.005s
PO␣#53,␣PROVABLE␣by␣trivial␣p␣in␣set␣(dom␣checklist)␣in␣0.001s
PO␣#54,␣MAYBE␣in␣0.006s
PO␣#55,␣MAYBE␣in␣0.0s
PO␣#56,␣MAYBE␣in␣0.001s
PO␣#57,␣MAYBE␣in␣0.001s
PO␣#58,␣MAYBE␣in␣0.001s
PO␣#59,␣MAYBE␣in␣0.001s
PO␣#60,␣MAYBE␣in␣0.001s
PO␣#61,␣MAYBE␣in␣0.001s
PO␣#62,␣MAYBE␣in␣0.0s
PO␣#63,␣PROVABLE␣by␣finite␣types␣in␣0.001s
PO␣#64,␣PROVABLE␣by␣finite␣types␣in␣0.001s
PO␣#65,␣PROVABLE␣by␣finite␣types␣in␣0.001s
PO␣#66,␣MAYBE␣in␣0.001s
>
*/
```

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